

Lecture 19 - Non-linear components, small-signal analysis

April 23rd, 2020

Contents:

1. Incremental analysis

Reading Assignment:

Agarwal and Lang, Ch. 4, § § 4.5, 4.6

Handouts:

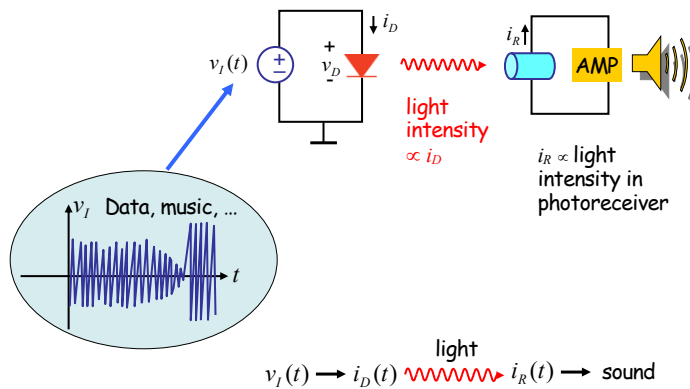
Lecture 19 notes

Announcements:

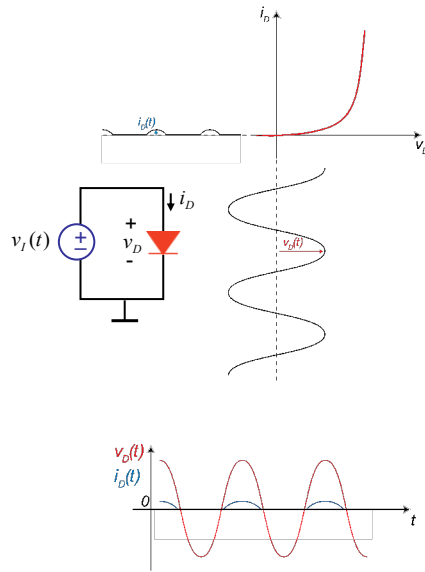
This lecture is being recorded and will be posted in the certificates-protected part of the 6.002 website

1. Incremental analysis

- Consider an optical transmission system



- Problem: LED is non linear \rightarrow distortion!

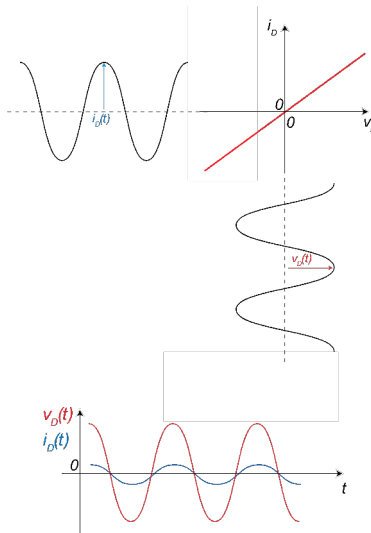


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- What we really want is linear characteristics for the LED!

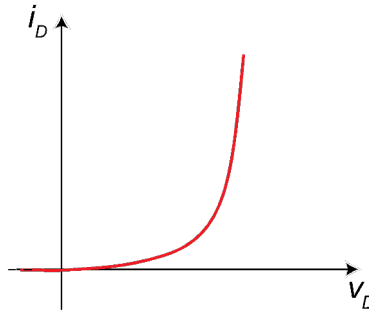


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How can we use a non-linear device as a linear one?

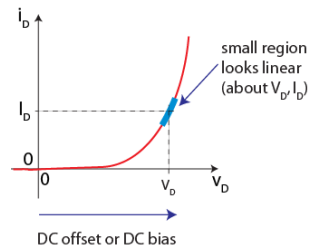


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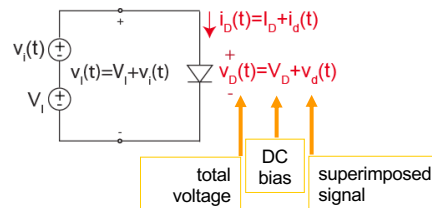
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- Insight: small region in i-v characteristics looks linear!



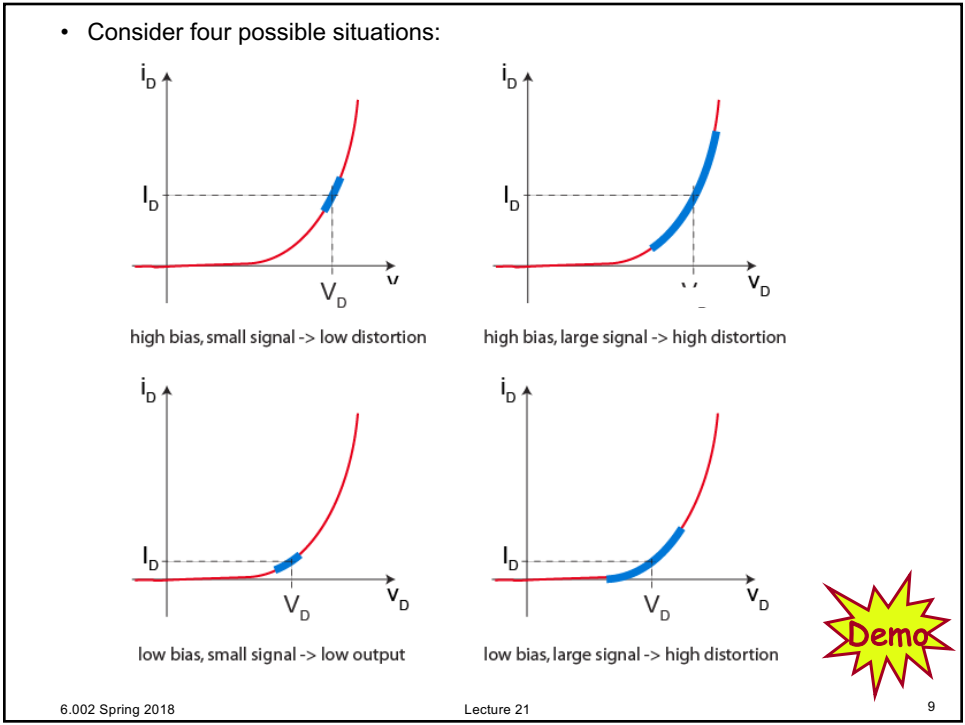
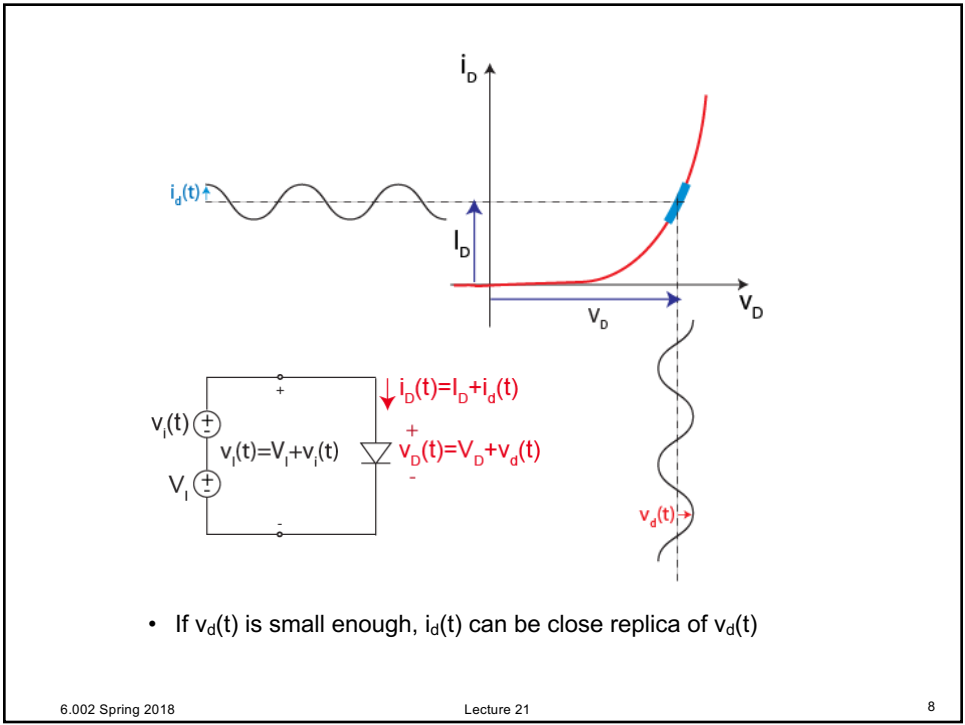
- Apply signal on top of *DC offset* or *DC bias*:



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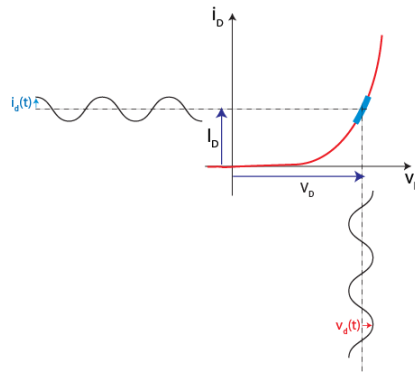
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Incremental analysis or small-signal method

- Interested in situations where signal has small magnitude:
→ want to know $i_d(t)$ in response to $v_d(t)$



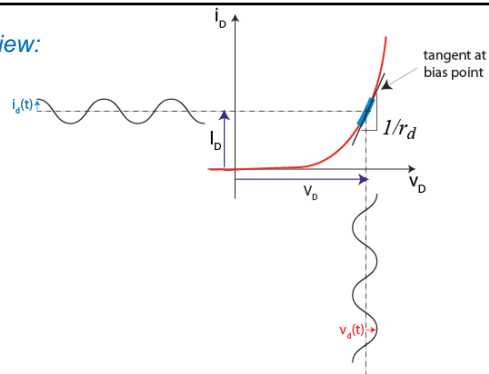
- Key insight: if $v_d(t)$ is small enough, device behavior is roughly linear
→ linearize device i-v characteristics

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1. The graphical view:



- Relationship between $v_d(t)$ and $i_d(t)$:

$$i_d(t) = \frac{1}{r_d} v_d(t)$$

With $r_d \equiv$ dynamic resistance:

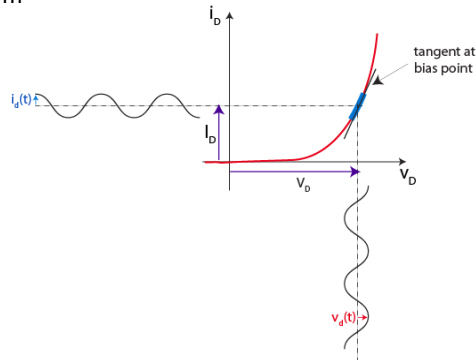
$$r_d(V_D) = \frac{1}{\left. \frac{df(v_D)}{dv_D} \right|_{v_D=V_D}}$$

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2. The mathematical description: do Taylor series expansion and select linear term



- In general terms, substitute:

$$i_D = f(v_D) = f(V_D + v_d) = I_S(e^{qv_D/kT} - 1)$$

- First three terms of Taylor series expansion:

$$i_D = f(V_D) + \frac{df(v_D)}{dv_D} \Big|_{v_D=V_D} \cdot v_d + \frac{1}{2} \frac{d^2f(v_D)}{dv_D^2} \Big|_{v_D=V_D} v_d^2 + \dots$$

- Then:

$$i_D = I_D + i_d = f(v_D) = f(V_D + v_d)$$

$$i_D \simeq f(V_D) + \frac{df(v_D)}{dv_D} \Big|_{v_D=V_D} \cdot v_d$$

- Identify terms:

- Bias (or operating point):

$$I_D = f(V_D)$$

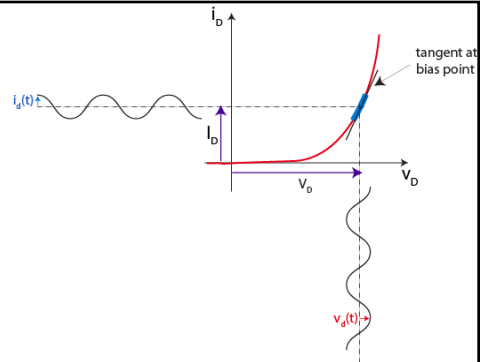
- Small signal:

$$i_d(t) = \frac{df(v_D)}{dv_D} \Big|_{v_D=V_D} \cdot v_d(t)$$

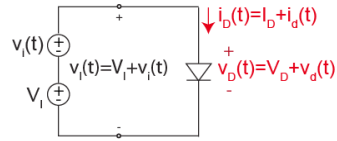
linear relation between $v_d(t)$ and $i_d(t)$.

- Proportionality constant between $v_d(t)$ and $i_d(t)$ has units of inverse resistance.

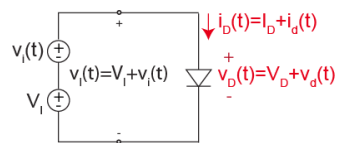
$$r_d(V_D) = \frac{1}{\frac{df(v_D)}{dv_D} \Big|_{v_D=V_D}}$$



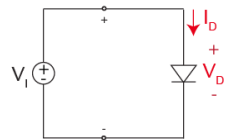
3. The circuit view: Small-signal technique effectively breaks problem into two simpler problems:



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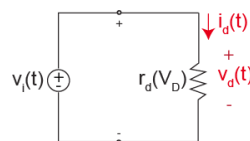
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bias circuit

Non-linear (but nothing is changing with time...)

+



small-signal or incremental circuit

Linear... we can use Superposition, homogeneity, Thevenin and Norton

Example

Consider diode with $I_S=1 \text{ pA}$ biased at $V_D=0.6 \text{ V}$ at room temperature. A signal with 1 mV amplitude is applied. What is the amplitude of the small-signal current?

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Consider diode with $I_S=1 \text{ pA}$ biased at $V_D=0.6 \text{ V}$ at room temperature. A signal with 1 mV amplitude is applied. What is the amplitude of the small-signal current?

Remember i-v characteristics of diode:

$$i_D = I_S(e^{qv_D/kT} - 1)$$

Dynamic resistance of diode:

$$r_d = \frac{1}{\frac{df(v_D)}{dv_D}\big|_{v_D=V_D}} = \frac{1}{I_S \frac{q}{kT} e^{qV_D/kT}\big|_{v_D=V_D}}$$

This can be simplified if we remember that, at bias point:

$$I_D = I_S(e^{qV_D/kT} - 1)$$

Then:

$$r_d = \frac{kT}{q(I_D + I_S)}$$

Compute I_D :

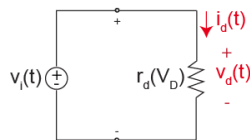
$$I_D \simeq 10^{-12} e^{0.6/0.026} = 11 \text{ mA}$$

Dynamic resistance:

$$r_d = \frac{kT}{q(I_D + I_S)} \simeq \frac{kT}{qI_D} = \frac{0.026}{0.011} = 2.4 \Omega$$

Small-signal current amplitude:

$$i_d = \frac{v_d}{r_d} = \frac{0.001}{2.4} = 0.42 \text{ mA}$$



- How “small” does the small signal need to be?

Analysis good if in Taylor series expansion:

Quadratic term \ll Linear term

$$\frac{1}{2} \frac{d^2 f(v_D)}{dv_D^2} \Big|_{v_D=v_D} v_d^2 \ll \frac{df(v_D)}{dv_D} \Big|_{v_D=v_D} \cdot v_d$$

$$\frac{1}{2} I_S \left(\frac{kT}{q} \right)^2 e^{qv_D/kT} \cdot v_d^2 \ll I_S \left(\frac{kT}{q} \right) e^{qv_D/kT} \cdot v_d$$

Or:

$$v_d \ll 2 \frac{kT}{q}$$

At room temperature, this implies:

$$v_d \ll 2 \times 0.026 = 0.052 \text{ V}$$

Summary

- Incremental or small-signal analysis: powerful technique suitable for situations with relatively “small” signals.
- Incremental or small-signal model: fully linearized model suitable to solve the small signal problem; can use many circuit solving techniques.
- Values of elements in small-signal model generally depend on the bias point.